

TITLE PHASE DETONATED SHOCK TUBE (PDST)

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PHASE DETONATED SHOCK TUBE (PFST)*

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I. INTRODUCTION

The simple, cylindrically imploding and axially driven fast shock tube (FST) has been a basic component in our high velocity penetrator (HVP) program. It is a powerful device that is capable of delivering a directed and very high pressure output that we have successfully employed to drive hypervelocity projectiles. The FST is configured from a hollow, high explosive (HE) cylinder, a low density Styrofoam core, and a one-point initiator at one end. A Mach stem is formed in the core as the forward propagating, HE detonation wave intersects the reflected radial wave. By proper arrangement of HE length and diameter, a steady state Mach stem is readily achieved at the output end. Production of HE is prevented by underdriving the Mach stem as it is being developed and this is most easily done by varying the foam density. The strength of the Mach stem is dependent on the effective energy transfer from the HE and this can be scaled geometrically. We have found this simple FST to be a powerful pressure multiplier. Typically, up to 1 Mbar output pressure can be obtained from this device. Further increase in the output pressure can be achieved by increasing the HE detonation velocity.

Over the last few years, the FST has been fine-tuned to drive a thin plate to very high velocity, on the order of 1000 m/sec. per unit area of about 1 Mbar μm^2 . Typically, a 1-cm-thick, 1-cm-dia disk has been accelerated intact to 1000 m/sec. under a loading pressure of several Mbar μm^2 . By making the plate on the side slightly convex at the loading side we have successfully accelerated it to about 1000 m/sec. By placing a thin layer of aluminum or beryllium on the back of a 1-cm-thick, 1-cm-dia titanium plate with an equivalent compliance, it has been accelerated to above

10000 m/sec. We have found the incorporation of a barrel at the end of the FST to be important. The confinement of the propellant gas by the barrel tends to accelerate the projectile to higher velocity. Furthermore, the standoff in the barrel between the plate and the FST allows the expanding gas to load more gently on the plate and thus reduces the loading pressure rate. A localized acceleration is highly desirable to prevent the plate from being broken up prematurely. However, presence of a large standoff volume tends to introduce wall effects and generate serious perturbation from the not well understood, high pressure gas flow dynamics. We try to mitigate this difficulty by keeping the standoff distance as short as can be tolerated by experimental tests. In general we have found good agreement between the 2D numerical simulation and measurements. Even scaling tests appear to be satisfactory. A factor of three increase in the geometric dimensions of the FST, barrel, standoff, and plate yields similar results in both the calculations and experiments.

The desire to accelerate the plate above 10000 m/sec. provides the impetus to develop a more advanced fast shock tube that will deliver a much higher output pressure. We decided to investigate a relatively simple but phase detonation system (PPSD) with fifty percent higher phase detonation velocity and a much higher output. Cyclic calculations show that the PSD acceleration of a plate to about 10000 m/sec. can be achieved. The performance of the PSD has been evaluated and the details are described below.

II. DESCRIPTION OF PHASE DETONATED FST

The phase detonated FST is hexamethylene tri-azide (C₆H₆N₆) phase detonation velocity component of a 10000 m/sec. phase III hexamethylene detonated on the left of the hemi-

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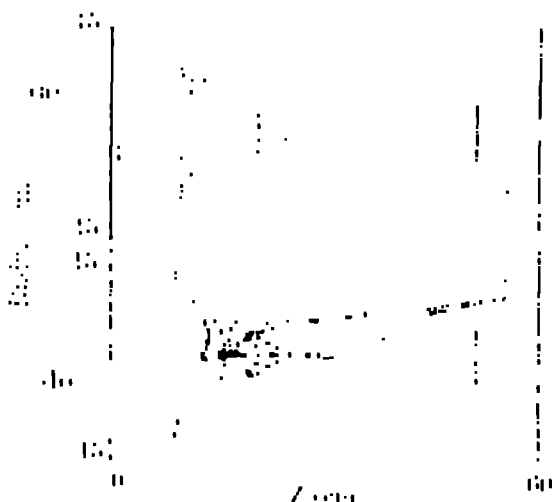


FIGURE 2
Phase detonated FSI with a disk showing (a) cup and (b) Mach disk formation process.

and it detonates the cylinder of Competition. It is the cup side surface of the FSI. As it detonation proceed to the right, a cylindrical shell of 300 stainless steel 3500 is propelled radially outward. It impinges on the conical surface of a 6061 aluminum plume lens, the angle of which determines the phase velocity of the cylinder. Thus, it is transmitted a shock to a cylindrical shell of PBX 9400 explosive and detonates it at an axial velocity determined by the phase

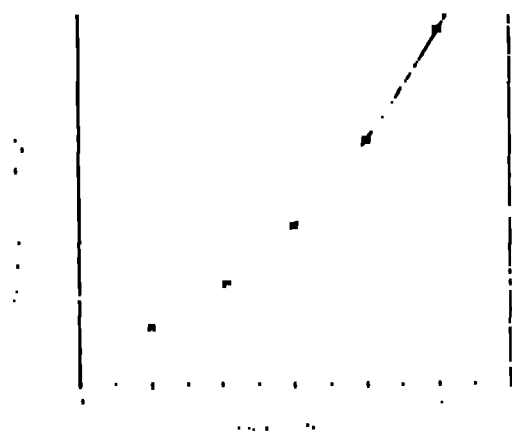


FIGURE 3
Calculated phase velocity as a function of cone angle for a PFI.

velocity vector. An axial cylinder of Styrofoam is then shock compressed by this travelling detonation front resulting in a Mach disk travelling at the same phase velocity. It ultimately breaks out of the system at the right end face and causes the acceleration of a 304SS plate placed against that face or suspended in a 304SS cup of that size against that face.

The purpose of the steel plate against the base of the PFI's lens, the polyethylene wedge against its periphery, and the polyethylene disk at the left face of the plume enclosure to prevent the predetonation of the PBX 9400 explosive before the shock from the collapse of 304SS cylinder detonates it. The plate of polyethylene on the left face of the Styrofoam results in a detonation distance for the full diameter formation of the Mach disk.

III. PHASE-DETONATION, MACH DISK PERFORMANCE

The hydrocode, Mead'D, has been used to model the overall performance of the phase detonated FSI. It is a 2-D, Eulerian, second order code that can handle multi-material problem and can treat the programmed detonation of high explosive. The results shown here have been obtained using a Cray Y 22P computer.

The modeling of a phase detonated FSI with a cup and a cylinder in Figure 2b, the linear collapse of the 300 stainless steel to the 6061 Al plume lens, shock in the lens, phase detonation of the PBX 9400 explosive and the shock location. The angle of the plume lens in the problem is 45 degree and the resultant phase velocity of the PBX 9400 detonation front is 1.10 cm/μs, an increase of 30% over the normal detonation velocity of 0.85 cm/μs. The shock velocity of the 300 stainless steel is 1.00 cm/μs, the same value of 1.00 cm/μs.

There is an alternative experiment. It is being planned to measure the phase velocity in the cylinder. The measurements to be accomplished are to be made directly against cable zero embedded at equal spaced intervals around an aluminum rod system of variable geometry probe that replaced the face of the plume lens. The probe is to be made of stainless steel. The probe is to be made of stainless steel. The probe is to be made of stainless steel.

and several grooves machined into the aluminum rod and then had their protruding outer ends carefully and precisely ground off, exposing the central coaxial conductor (Fig. 3). As the phase detonation proceeded along the PBX 9501 explosive, the cables were inserted and through an interferometry circuit the position vs. time data of the two cables was determined. The velocity was then extracted from the x-t data.

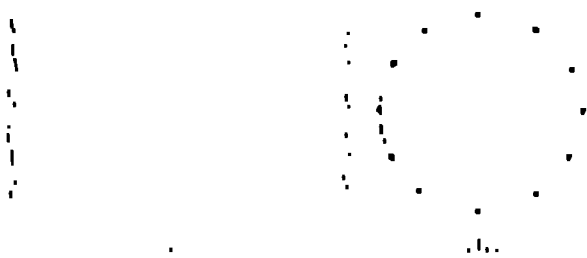


FIGURE 3

Side-on and end-on views of microwave interferometry probe used to determine plate velocity.

A plot of the detonation velocity average of the channel is shown in Figure 4. The plate velocity is approximately 1.47 cm/μs, which is acceptable, due to the experimental velocity of 1.40 cm/μs. The data was then digitally averaged.

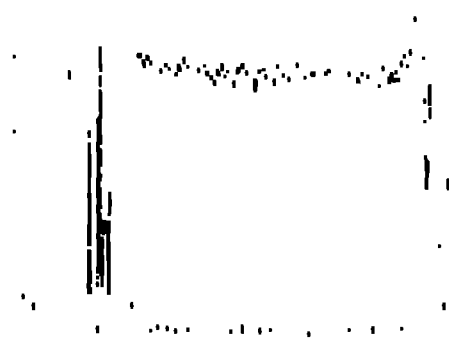


FIGURE 4

Average detonation velocity and time measured by interferometry.

IV. PLATE ACCELERATION PERFORMANCE

Because of the poor results obtained when trying to accelerate a plate down a barrel it was decided to attempt (with a vertical test system) to accelerate a plate initially in contact with the shock tube face and having convex plate curvature toward the shock tube face as shown in Figure 5. The plate is 0.15 cm thick, 301SS and on the two systems studied the radii of curvature of the plate faces against the shock tube were 11.36 cm and 6.77 cm. Hydrocalculations in these two systems are shown in overlays on Figure 5. The effect of decreasing the radius of curvature is evident in the greater consolidation, thickness, and increased forward bowing. The plate velocities are 1.26 and 1.20 cm/μs for the large and the short radius of curvature plates, respectively.

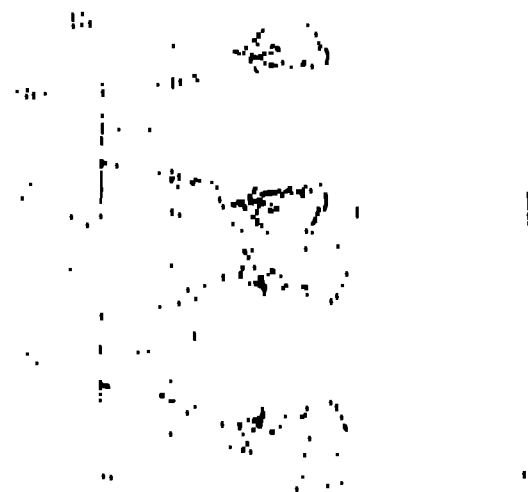


FIGURE 5

Effect of calculated plate curvature of 11.36 cm, 6.77 cm, for phase detonated 1.47 cm/sec barrel. The radii of curvature of the plate were 11.36 cm and 6.77 cm.

Experiments were performed on shock tube with the convexity of curvature machined on the plate surface. A hydrodynamic velocity of 500 m/sec between the shock tube and PBX 9501. The plate is 1.49 cm and 0.15 cm thick, and radii of curvature of 11.36 cm and 6.77 cm, respectively.

The experimental setup for the e-shots is shown in Figure 6. The assemblies accelerated the plates vertically downward. The displacements of the plates at the 3- μ s-ray times (95 and 361 em) were greater than the largest displacements shown in the hydrocode simulation (633 em in both calculations) in order to protect the x-ray head and the film cassette from blast and impact.

The radiographic results for the e-shots are given in Figure 7. Only one exposure was obtained for shot 56-435 because only one channel of the film x-ray unit operated. But a plate velocity was obtained for this shot by time information on initial motion time obtained from hydrocalculations and the earlier shot fired. The velocity of the plate in shot 56-435 is 1.8 cm μ ⁻¹ and the velocity of the negative part of the tip in shot 56-435 is 1.16 cm μ ⁻¹.

The difference in the calculated and experimental plate contours for the plate with 1137 em radius of curvature (Figure 5a and 6a) caused by early fracture of the plate at its periphery (not modeled by the hydrocode) reducing the driving pressure that resists and causes it to lag behind the plate center (which case is seen in Figure 6). Although the same peripheral pressure drop exists for the plate with the smaller radius of curvature, the consequences are much greater that it folds forward and collapses (see the results in Figure 5b) where larger displacements are needed to reach the case. The plate in both of the e-shots may be related to the results obtained to be after the initial



FIGURE 6
Experimental setup for e-shots of 95 and 361 μ s.



FIGURE 7
Radiograph of thin lead plate moving to the right in shot 56-435 and the shot 56-435. Obvious oblation of plate in (a) can be seen to form a fold.

hydrocode calculation into completed and the plate is broken at one position.

V. CONCLUSIONS

Detonation of PBX 9402 at a plate velocity of 2.10 cm μ ⁻¹ has been observed, and the detonation velocity was uniform at P₁ positions around the inner cylindrical section. A Mach disk in an axial symmetry cylinder within the explosive was formed and traveled at the same plate velocity. From our hydrocode, caused by the beam-explosive interface, was eliminated by firing the shot vertically and placing a low velocity stream in the interface gap. A radius of curvature of 1137 em on the dynamic face of a 7% plate in contact with the beam III face of a shock tube produced plate convergence during acceleration and allowed the plate to reach a velocity of 1.1 cm μ ⁻¹. The only two edges of the plate indicate it may have folded. An arrangement with a barrel of appropriate length will allow the shock tube to accelerate a plate to a velocity and impact.